

# Introduction to neutrino mass models

## Lecture 3: TBM from $A_4$ symmetry

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January 8-11, 2018



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# PMNS matrix

# Quark masses in SM: single generation

Yukawa interactions provide masses to quarks:

$$\begin{aligned}
 -\mathcal{L}_Y^{(d)} &= y_d(\bar{Q}_L\Phi d_R + \bar{d}_R\Phi^\dagger Q_L) \rightarrow y_d(\bar{u}_L, \bar{d}_L) \begin{pmatrix} 0 \\ \frac{v}{\sqrt{2}} \end{pmatrix} d_R + h.c. \\
 &= \frac{y_d v}{\sqrt{2}}(\bar{d}_L d_R + \bar{d}_R d_L) \equiv m_d \bar{d}d.
 \end{aligned}$$

$$-\mathcal{L}_Y^{(u)} = y_u(\bar{Q}_L\tilde{\Phi} u_R + \bar{u}_R\tilde{\Phi}^\dagger Q_L) \rightarrow y_u(\bar{u}_L, \bar{d}_L) \begin{pmatrix} \frac{v}{\sqrt{2}} \\ 0 \end{pmatrix} u_R + h.c. \equiv m_u \bar{u}u.$$

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# Quark masses and mixing

Three generations  $Q_{Li}$ ,  $d_{Ri}$ ,  $u_{Ri}$ ,  $i = 1, 2, 3$ :

$$d_i = (d, s, b) \quad u_i = (u, c, t).$$

Yukawa interactions are parametrized with coupling matrices  $\Gamma_{ij}$  and  $\Delta_{ij}$ :

$$\begin{aligned} -\mathcal{L}_Y &= \bar{Q}_{Li} \Gamma_{ij} \Phi d_{Rj} + \bar{Q}_{Li} \Delta_{ij} \tilde{\Phi} u_{Rj} + h.c. \\ &\rightarrow \bar{d}_{Li} (M_d)_{ij} d_{Rj} + \bar{u}_{Li} (M_u)_{ij} u_{Rj} + h.c. \end{aligned}$$

where the  $3 \times 3$  mass matrices are

$$(M_d)_{ij} = \Gamma_{ij} \frac{v}{\sqrt{2}}, \quad (M_u)_{ij} = \Delta_{ij} \frac{v}{\sqrt{2}}$$

and are, in general, non-diagonal and complex.

## CKM matrix

$M_d$  is diagonalized by  $d_L = V_{dL} d_L^{phys}$ ,  $d_R = V_{dR} d_R^{phys}$ , and so is  $M_u$ :

$$V_{dL}^\dagger M_d V_{dR} = D_d = \text{diag}(m_d, m_s, m_b),$$

$$V_{uL}^\dagger M_u V_{uR} = D_u = \text{diag}(m_u, m_c, m_t),$$

But then the charged current matrix can become non-trivial:

$$\bar{u}_{Li} \gamma^\mu W_\mu^+ d_{Li} = \bar{u}_{Li}^{phys} \gamma^\mu W_\mu^+ V_{ij} d_{Lj}^{phys}, \quad \text{where} \quad V_{ij} = V_{uL}^\dagger V_{dL} \neq \delta_{ij}.$$

## Conclusion

if coupling matrices  $\Gamma_{ij}$  and  $\Delta_{ij}$  are distinct,  
then quark **mass eigenstates**  $\neq$  **charged current eigenstates**.

The **CKM matrix**  $V$  (Cabibbo-Kobayashi-Maskawa mixing matrix) describes how charged currents mix quarks from different generations.

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# Lepton mixing: Dirac

Massive neutrinos implies that they are either **Dirac** or **Majorana**.

For **Dirac neutrinos**, we add  $\nu_{Ri}$ ,  $i = 1, 2, 3$ , write only Dirac mass term, get lepton mass matrices  $M_\ell$  and  $\mathcal{M}_\nu$ , and diagonalize them as before:

$$U_{\ell L}^\dagger M_\ell U_{\ell R} = D_\ell = \text{diag}(m_e, m_\mu, m_\tau),$$

$$U_{\nu L}^\dagger \mathcal{M}_\nu U_{\nu R} = D_\nu = \text{diag}(m_1, m_2, m_3),$$

The charged weak currents are written in the generation space as

$$\underbrace{\overline{\ell_{Li}} \gamma^\mu W_\mu^- \nu_{Li}}_{\text{original}} = \underbrace{(\overline{e_L}, \overline{\mu_L}, \overline{\tau_L}) \gamma^\mu W_\mu^-}_{\text{flavor basis}} \begin{pmatrix} \nu_e \\ \nu_\mu \\ \nu_\tau \end{pmatrix} \equiv (\overline{e_L}, \overline{\mu_L}, \overline{\tau_L}) \gamma^\mu W_\mu^- U_{PNMS} \begin{pmatrix} \nu_1 \\ \nu_2 \\ \nu_3 \end{pmatrix}$$

# Lepton mixing: Dirac

$$\underbrace{\overline{\ell_{Li}} \gamma^\mu W_\mu^-}_{\text{original}} \nu_{Li} = \underbrace{(\overline{e_L}, \overline{\mu_L}, \overline{\tau_L}) \gamma^\mu W_\mu^-}_{\text{flavor basis}} \begin{pmatrix} \nu_e \\ \nu_\mu \\ \nu_\tau \end{pmatrix} \equiv (\overline{e_L}, \overline{\mu_L}, \overline{\tau_L}) \gamma^\mu W_\mu^- U_{PMNS} \begin{pmatrix} \nu_1 \\ \nu_2 \\ \nu_3 \end{pmatrix}$$

Flavor basis is defined as the charged lepton mass basis:

$$\ell_{Li} = U_{\ell} \ell_L^{\text{mass}}, \quad \nu_{Li} = U_\nu \nu_L^{\text{mass}}$$

Therefore, the Pontecorvo-Maki-Nakagawa-Sakata mixing matrix is

$$U_{PMNS} = U_\ell^\dagger U_\nu.$$

If  $M_\ell$  is already diagonal, then  $U_{PMNS} = U_\nu$ .

# Lepton mixing: Dirac

$$\begin{pmatrix} \nu_e \\ \nu_\mu \\ \nu_\tau \end{pmatrix} = U_{PMNS} \begin{pmatrix} \nu_1 \\ \nu_2 \\ \nu_3 \end{pmatrix}.$$

After removing phases, the standard parametrization is

$$U_{PMNS} = \begin{pmatrix} c_{12}c_{13} & s_{12}c_{13} & s_{13}e^{-i\delta} \\ -s_{12}c_{23} - c_{12}s_{13}s_{23}e^{i\delta} & c_{12}c_{23} - s_{12}s_{13}s_{23}e^{i\delta} & c_{13}s_{23} \\ s_{12}s_{23} - c_{12}s_{13}c_{23}e^{i\delta} & -c_{12}s_{23} - s_{12}s_{13}c_{23}e^{i\delta} & c_{13}c_{23} \end{pmatrix}$$

Since  $\mathcal{M}_\nu$  is diagonalized by **bi-unitary** transformation

$$U_{\nu L}^\dagger \mathcal{M}_\nu U_{\nu R} = D_\nu = \text{diag}(m_1, m_2, m_3),$$

some phases from  $U_{\nu L}$  can be moved to  $U_{\nu R}$ .

PMNS matrix  $U_{PMNS}$  contains only one irremovable phase.

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# Lepton mixing: Majorana

For **Majorana neutrinos**, the mass matrix is

$$\nu_{Li}^T (\mathcal{M}_\nu)_{ij} \nu_{Lj} = (\nu_L^{\text{mass}})^T U_\nu^T \mathcal{M}_\nu U_\nu \nu_L^{\text{mass}} = (\nu_L^{\text{mass}})^T D_\nu \nu_L^{\text{mass}}$$

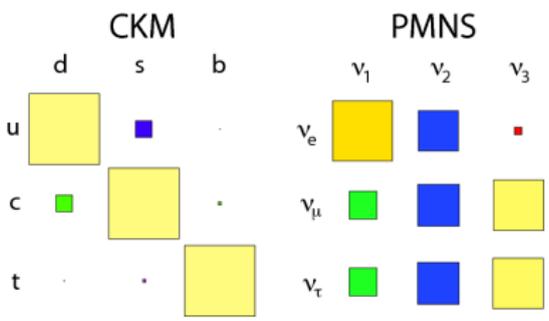
with the same matrix  $U_\nu$  on both sides.

One can always find such  $U_\nu$  to make  $D_\nu$  diagonal with real positive values. But once this is done, **there is no freedom left to remove phases!**

$$U_{PMNS}^{\text{Majorana}} = U_{PMNS} \cdot \begin{pmatrix} 1 & 0 & 0 \\ 0 & e^{i\alpha} & 0 \\ 0 & 0 & e^{i\beta} \end{pmatrix}.$$

These **two additional Majorana phases** are the echo of the complex neutrino mass matrix  $\mathcal{M}_\nu$ .

# Lepton mixing



$U_{PMNS}$  is close to the **tri-bimaximal mixing pattern** [Harrison, Perkins, Scott, 2002]:

$$U_{TBM} = \begin{pmatrix} \sqrt{\frac{2}{3}} & \frac{1}{\sqrt{3}} & 0 \\ -\frac{1}{\sqrt{6}} & \frac{1}{\sqrt{3}} & \frac{1}{\sqrt{2}} \\ -\frac{1}{\sqrt{6}} & \frac{1}{\sqrt{3}} & -\frac{1}{\sqrt{2}} \end{pmatrix}$$

Nonzero  $s_{13}$  highlights deviation, but proximity of  $U_{PMNS}$  to the TBM is indicative of some symmetry.

# Basics of finite group theory

# Groups

Set  $G$  is a group if it satisfies the following four axioms:

- **closure** of  $G$  under composition (usually called **multiplication**):

for any  $g_1, g_2 \in G$ , define their product  $g_1 \cdot g_2 \in G$ ;

- the multiplication is **associative**:  $g_1 \cdot (g_2 \cdot g_3) = (g_1 \cdot g_2) \cdot g_3$  for all  $g_1, g_2, g_3 \in G$ ;
- there exists a special element called **identity element**  $e$  with the properties:

$$g \cdot e = e \cdot g = g \quad \text{for any } g \in G;$$

- every element is **invertible**: for any  $g \in G$ , there exists another element in  $G$  (denoted  $g^{-1}$ ) such that

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# Groups

In addition, if  $g \cdot h = h \cdot g$  for all elements  $g, h \in G$ , the group is called **abelian**. If it fails at least for one pair, the group is called **non-abelian**.

Non-abelian groups are much, much, **much** more complicated than abelian groups.

Groups arise in physics in the context of **transformations** and **symmetries**. It is the most appropriate language to describe hidden consequences of physics formulas or laws.

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# Groups

Groups can be **finite** or **infinite**.

- A finite group  $G$  has finite number of elements:  $G = \{e, g_2, g_3, \dots, g_n\}$ . Its size  $n$  is called the **order of the group** and is denoted  $|G|$ .
- In a finite group, successive multiplications will sooner or later terminate in  $e$ . Pick up any  $g \in G$  and consider successive powers:

$$g^1 \equiv g \quad g^2 \equiv g \cdot g, \quad g^3 \equiv g \cdot g \cdot g, \quad g^k \equiv \underbrace{g \cdot \dots \cdot g}_{k \text{ times}}.$$

Then, there must exist an integer  $p$  such that  $g^p = e$ . This integer  $p$  is called the **order of the element**  $g$ .

- **Infinite** groups can be **discrete** or continuous (= topological).

# Basics examples

- Integers  $\mathbb{Z}$  and reals  $\mathbb{R}$  are groups under addition. The identity element is 0. They are **not** groups under multiplication!
- Reals on the interval  $[0, 1]$  form a group under addition with periodic boundary condition ( $0.999\cdots = 0$ ). These are fractional part of reals:  $\mathbb{R}/\mathbb{Z}$ .  
Complex numbers with  $|z| = 1$  form under multiplication the **circle group**, or the **rephasing group**  $U(1)$ .  
The two last groups are **isomorphic**:  $\mathbb{R}/\mathbb{Z} \simeq U(1)$ .
- **Cyclic groups**  $\mathbb{Z}_n$  for any  $n > 1$  are defined as

$$\mathbb{Z}_n = \{e, a, a^2, a^3, \dots, a^{n-1}\} \quad \text{with condition } a^n = e,$$

isomorphic to integers modulo  $n$  under addition:  $\mathbb{Z}/n\mathbb{Z}$ .

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# Presentation of a group

How would you describe a finite group?

Simplest choice: write the multiplication table  $|G| \times |G|$ . Very impractical.

Much better choice: via **generators** and **relations**.

- **Generators**  $a, b, c, \dots$  form a subset of elements of  $G$  such that any  $g \in G$  can be written and their product.
- Generators are independent elements but they satisfy some constraints (relations).
- **Group presentation**:  $G = \langle \text{generators} \mid \text{their relations} \rangle$ .
- A cyclic group is generated by  $a$ :  $\mathbb{Z}_n = \langle a \mid a^n = e \rangle$ .  
Direct product of cyclic groups:  $\mathbb{Z}_n \times \mathbb{Z}_m = \langle a, b \mid a^n = b^m = e, ab = ba \rangle$ .

# Representations of abelian groups

A **representation** of the group  $G$  is, colloquially speaking, a way of rewriting it as a **group of matrices** which act on some  $k$ -dimensional vector space.

The set of matrices **must obey exactly the same rules** as the elements of  $G$ , but otherwise there is no constraints on their form or dimension  $k$ . For example,

$$\mathbb{Z}_2 = (e, a) : \quad a = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \quad \text{or} \quad \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

$$\mathbb{Z}_3 = (e, b, b^2) : \quad b = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{pmatrix} \quad \text{or} \quad \begin{pmatrix} 1 & 0 & 0 \\ 0 & \omega & 0 \\ 0 & 0 & \omega^2 \end{pmatrix} .$$

where  $\omega \equiv \exp(2\pi i/3)$ ,  $\omega^3 = 1$ .

# Representations of abelian groups

General theorem: for any **abelian** unitary group, the representing matrices **can be always made diagonal** by a basis choice.

Example:  $\mathbb{Z}_2 \times \mathbb{Z}_2 = (e, a, b, ab)$  with a faithful 2D representation:

$$e = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}, \quad a = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}, \quad b = \begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix}, \quad ab = \begin{pmatrix} -1 & 0 \\ 0 & -1 \end{pmatrix}.$$

In this basis, each 1D subspace remains invariant; and the diagonal numbers form a 1D representation.

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# Working example: $A_4$

# Non-abelian groups

There is a much richer list of (finite) non-abelian groups. Some examples:

- $S_n$ , group of all permutations of  $n$  elements. Its order is  $|S_n| = n!$ . The smallest group is  $S_2 \simeq \mathbb{Z}_2$ . The smallest **non-abelian** is

$$S_3 = \langle a, b | a^2 = b^3 = e, ab = b^2 a \rangle.$$

- $A_n$ , group of **even-signature permutations** of  $n$  elements;  $|A_n| = n!/2$ .
- Symmetry groups of regular **polygons** and **polyhedra**:
  - Symmetry group of **equilateral triangle**  $\simeq S_3$ ;
  - Symmetry group of **tetrahedron**  $\simeq A_4$ ;
  - Symmetry group of **cube**  $\simeq S_4$ .

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# Group $A_4$

$A_4$  is the smallest group with irreducible 3D representation:

$$A_4 = \langle S, T | S^2 = T^3 = e, (ST)^3 = e \rangle, \quad |A_4| = 12.$$

It contains:

- three elements of order 2:  $S, T^2ST, TST^2$ ;
- together with  $e$ , they form the Klein subgroup  $\mathbb{Z}_2 \times \mathbb{Z}_2$ ;
- four cycles of order 3 generated by  $T, ST, TS, T^2ST^2$  (8 elements of order 3 in total).

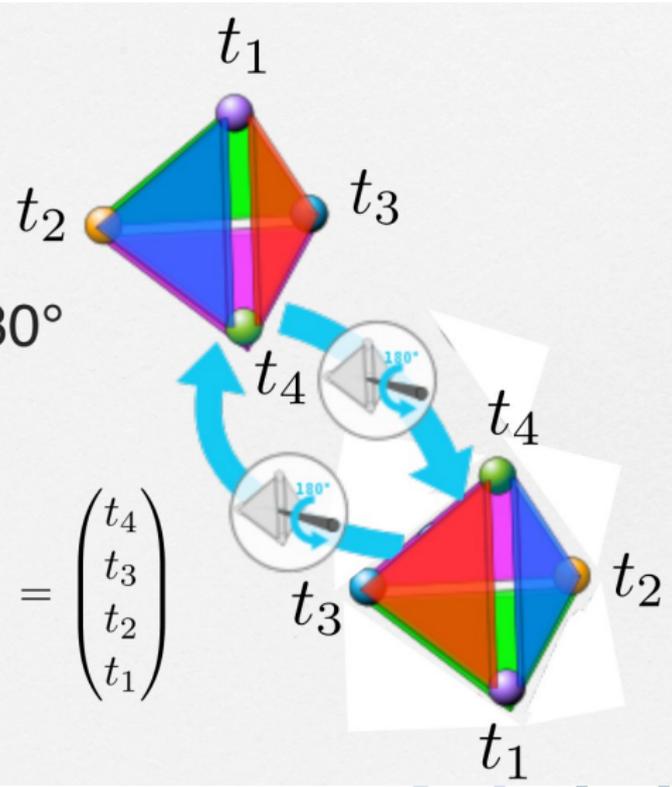
# $A_4$ : transformation $S$

# $A_4$

• rotation by  $180^\circ$

$S$

$$\begin{pmatrix} 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} t_1 \\ t_2 \\ t_3 \\ t_4 \end{pmatrix} = \begin{pmatrix} t_4 \\ t_3 \\ t_2 \\ t_1 \end{pmatrix}$$



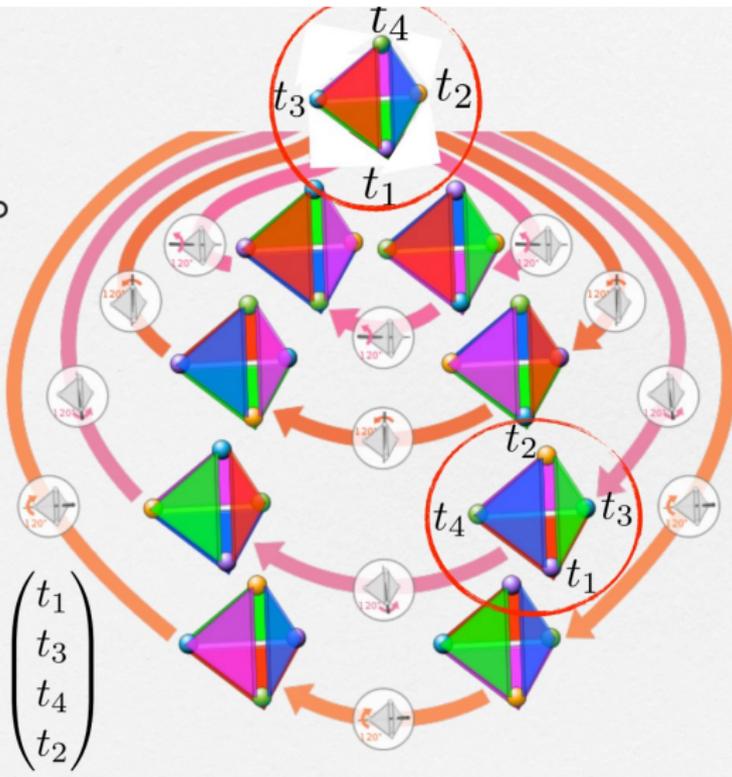
# $A_4$ : transformation $T$

# $A_4$

- rotation by  $120^\circ$  anti-clockwise (seen from a vertex)

$$T$$

$$\begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 1 & 0 & 0 \end{pmatrix} \begin{pmatrix} t_1 \\ t_2 \\ t_3 \\ t_4 \end{pmatrix} = \begin{pmatrix} t_1 \\ t_3 \\ t_4 \\ t_2 \end{pmatrix}$$



# Group $A_4$

3D irreducible representation: **diagonal-S basis**

- order 2:

$$S = \begin{pmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & -1 \end{pmatrix}, \quad T^2ST = \begin{pmatrix} -1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -1 \end{pmatrix} \quad TST^2 = \begin{pmatrix} -1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

- order 3:

$$T = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{pmatrix}, \quad ST = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & -1 \\ -1 & 0 & 0 \end{pmatrix},$$

$$TS = \begin{pmatrix} 0 & -1 & 0 \\ 0 & 0 & -1 \\ 1 & 0 & 0 \end{pmatrix}, \quad T^2ST^2 = \begin{pmatrix} 0 & -1 & 0 \\ 0 & 0 & 1 \\ -1 & 0 & 0 \end{pmatrix},$$

and their squares.

# Group $A_4$

3D irreducible representation: **diagonal- $T$  basis**

One can switch to another basis in the same 3D space, in which  $T$  becomes diagonal.

$$T = \begin{pmatrix} 1 & 0 & 0 \\ 0 & \omega & 0 \\ 0 & 0 & \omega^2 \end{pmatrix}, \quad \omega \equiv e^{2\pi i/3}, \quad \omega^3 = 1.$$

Then,  $S$  takes an “ugly” shape:

$$S = \frac{1}{3} \begin{pmatrix} -1 & 2 & 2 \\ 2 & -1 & 2 \\ 2 & 2 & -1 \end{pmatrix}.$$

Nevertheless, all group multiplications hold:  $S^2 = e$ , etc

# Group $A_4$

Subspaces in the diagonal- $T$  basis are convenient to define three non-equivalent 1D irreps:  $1, 1', 1''$

The full table of all irreps of  $A_4$ :

irrep	$S$	$T$
1	$S = 1$	$T = 1$
$1'$	$S = 1$	$T = \omega$
$1''$	$S = 1$	$T = \omega^2$
3	matrix $S$	matrix $T$

Notice: the trivial singlet 1 is **invariant under the entire  $A_4$** .



# Tensor product decomposition

Models begin with lagrangian  $\mathcal{L}$ , which encodes all interactions.

Terms in the lagrangian are products of various fields:

$$\mathcal{L} = \dots + \lambda_5 (\Phi_1^\dagger \Phi_2)^2 + \dots + Y_{ij}^a \overline{Q_{Li}} \Phi_a d_{Rj} + \dots$$

We assume that each set of fields (LH fermions, RH fermions, Higgses, etc) **transforms as a certain representation** of group  $G$ .

We want to find which combinations are fully  $G$ -invariant.

We must use the **tensor product of representations**.

# Tensor product decomposition

Take 3D vectors  $a_i = (a_1, a_2, a_3)$  and  $b_j = (b_1, b_2, b_3)$  and construct their **tensor product**  $a_i b_j$ . How does it transform under  $SO(3)$  rotations?

$$a_i b_j = \delta_{ij} \frac{(\vec{a}\vec{b})}{3} + \epsilon_{ijk} \cdot \underbrace{v_k}_{=[\vec{a} \times \vec{b}]/2} + \left[ \frac{1}{2} (a_i b_j + a_j b_i) - \delta_{ij} \frac{(\vec{a}\vec{b})}{3} \right],$$

which means that inside the 9D tensor  $a_i b_j$  there are three invariant subspaces: **singlet**,  $\propto \delta_{ij}$ ; **triplet**,  $\propto \epsilon_{ijk} v_k$ , and **5-plet**, the traceless symmetric part of  $a_i b_j$ .

Group-theoretically:  $3 \otimes 3 = 1 \oplus 3 \oplus 5$ .

This is how tensor product decomposition (= Clebsch-Gordan coeffs) works in the group  $SO(3)$ .

# Tensor product decomposition

For each group, these rules are different (= Clebsch-Gordan coefs are different).

For  $A_4$ , if  $a = (a_1, a_2, a_3)$  and  $b = (b_1, b_2, b_3)$  are two irreducible triplets, then

$$3 \otimes 3 = 1 \oplus 1' \oplus 1'' \oplus 3_1 \oplus 3_2 .$$

The explicit expressions for their components (in the  $S$ -symmetric basis!) are:

$$\begin{aligned} 1 &= a_1 b_1 + a_2 b_2 + a_3 b_3 , \\ 1' &= a_1 b_1 + \omega^2 a_2 b_2 + \omega a_3 b_3 , \\ 1'' &= a_1 b_1 + \omega a_2 b_2 + \omega^2 a_3 b_3 , \\ 3_1 &= (a_2 b_3, a_3 b_1, a_1 b_2) , \\ 3_2 &= (a_3 b_2, a_1 b_3, a_2 b_1) . \end{aligned}$$

The products of **singlets** are intuitive:  $1' \otimes 1'' = 1$ , etc.

# Picking up symmetric terms

When building symmetry-constrained lagrangians, we

- write products of fields, each transforming as a certain irrep of the group  $G$ ,
- perform tensor product decomposition,
- out of all final irreps, **keep only trivial singlets** as they are  $G$ -symmetric.

For example, in three-Higgs-doublet model based on group  $A_4$ , we have three Higgs doublets  $\Phi_1, \Phi_2, \Phi_3$ . In general, the quadratic part of the potential has nine terms  $\Phi_i^\dagger \Phi_j$ .

But knowing that, for the group  $A_4$ ,  $3 \otimes 3 = 1 \oplus 1' \oplus 1'' \oplus 3_1 \oplus 3_2$ , we keep only the singlet. Therefore, the Higgs potential is

$$V = -m^2 \left( \Phi_1^\dagger \Phi_1 + \Phi_2^\dagger \Phi_2 + \Phi_3^\dagger \Phi_3 \right) + V_4$$

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# Picking up symmetric terms

For the quartic part, we decompose  $(\Phi_i^\dagger \Phi_j)(\Phi_k^\dagger \Phi_l)$ ,

$$\begin{aligned} [(3 \otimes 3) \otimes (3 \otimes 3)]_{sym} &= [(1 \oplus 1' \oplus 1'' \oplus 3_1 \oplus 3_2) \otimes (1 \oplus 1' \oplus 1'' \oplus 3_1 \oplus 3_2)]_{sym} \\ &= \mathbf{1} \otimes \mathbf{1} + \mathbf{1}' \otimes \mathbf{1}'' + \underbrace{(3_1 \otimes 3_1)}_{=1 \oplus \dots} + \underbrace{(3_2 \otimes 3_2)}_{=1 \oplus \dots} + \underbrace{(3_1 \otimes 3_2)}_{=1 \oplus \dots} + \dots, \end{aligned}$$

which gives five trivial singlets **1**:

$$\begin{aligned} V_4 &= \lambda_1 \left( \Phi_1^\dagger \Phi_1 + \Phi_2^\dagger \Phi_2 + \Phi_3^\dagger \Phi_3 \right)^2 \\ &+ \lambda_2 \left[ (\Phi_1^\dagger \Phi_1)(\Phi_2^\dagger \Phi_2) + (\Phi_2^\dagger \Phi_2)(\Phi_3^\dagger \Phi_3) + (\Phi_3^\dagger \Phi_3)(\Phi_1^\dagger \Phi_1) \right] \\ &+ \lambda_3 \left[ (\Phi_1^\dagger \Phi_2)(\Phi_2^\dagger \Phi_1) + (\Phi_2^\dagger \Phi_3)(\Phi_3^\dagger \Phi_2) + (\Phi_3^\dagger \Phi_1)(\Phi_1^\dagger \Phi_3) \right] \\ &+ \left( \lambda_4 \left[ (\Phi_1^\dagger \Phi_2)^2 + (\Phi_2^\dagger \Phi_3)^2 + (\Phi_3^\dagger \Phi_1)^2 \right] + h.c. \right) \end{aligned}$$

# Spontaneous symmetry breaking

In this way, we get the **full  $A_4$ -symmetric potential in 3HDM**.

But the minimum of this potential  $(v_1, v_2, v_3)$  may break this group, fully or completely. Which options are available for the minimum in the  $A_4$ -symmetric 3HDM?

It turns out that vevs  $(v_1, v_2, v_3)$  **cannot be arbitrary!** Depending on parameters  $\lambda$ , only four **vev alignments** are possible [Degee, Ivanov, Keus, 2012]:

- $(1, 0, 0)$ . The residual symmetry group is  $\mathbb{Z}_2 \times \mathbb{Z}_2$ .
- $(1, 1, 1)$ . The residual symmetry group is  $\mathbb{Z}_3$ .
- $(1, \omega, \omega^2)$ . The residual symmetry group is  $\mathbb{Z}_3$ .
- $(1, e^{i\alpha}, 0)$ . The residual symmetry group is  $\mathbb{Z}_2$ .

Conclusion: **it is impossible** to break the  $A_4$  symmetry completely.

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# Extending $A_4$ 3HDM to charged leptons

Extending  $A_4$  symmetry of 3HDM to the [Majorana LH neutrino mass matrix](#) [Gonzales Felipe, Serodio, Silva, 2013].

Charged lepton Yukawa interactions:

$$\bar{L}_i Y_{ij}^a \underbrace{\Phi_a}_3 \ell_{Rj} + h.c.$$

We know that  $\Phi_a = (\Phi_1, \Phi_2, \Phi_3)$  transforms as triplet **3** under  $A_4$ .

Therefore, the product of  $L_i$  and  $\ell_{Rj}$  must also transform as a triplet **3** to produce the trivial singlet **1** at the end.

$L_i$	$\ell_{Rj}$
3	3
$(1, 1', 1'')$	3
3	$(1, 1', 1'')$

# Extending $A_4$ 3HDM to charged leptons

For example, if  $\bar{L}_i \sim (1, 1', 1'')$  and  $l_{Rj} \sim 3$ , we get:

$$\begin{aligned} \bar{L}_i Y_{ij}^a \Phi_a l_{Rj} &= y_1 \bar{L}_1 \underbrace{\Phi_a l_{Rj}}_1 + y_2 \bar{L}_2 \underbrace{\Phi_a l_{Rj}}_{1''} + y_3 \bar{L}_3 \underbrace{\Phi_a l_{Rj}}_{1'} \\ &= y_1 \bar{L}_1 (\Phi_1 l_{R1} + \Phi_2 l_{R2} + \Phi_3 l_{R3}) \\ &\quad + y_2 \bar{L}_2 (\Phi_1 l_{R1} + \omega \Phi_2 l_{R2} + \omega^2 \Phi_3 l_{R3}) \\ &\quad + y_3 \bar{L}_3 (\Phi_1 l_{R1} + \omega^2 \Phi_2 l_{R2} + \omega \Phi_3 l_{R3}) \end{aligned}$$

Pick up a vev alignment, for example,  $v(1, 1, 1)$ . Then, charged lepton mass matrix is

$$M_\ell = v \begin{pmatrix} y_1 & y_1 & y_1 \\ y_2 & \omega y_2 & \omega^2 y_2 \\ y_3 & \omega^2 y_3 & \omega y_3 \end{pmatrix},$$

which, after diagonalization gives  $m_\ell = \{y_1 v, y_2 v, y_3 v\} \rightarrow \text{OK}$ .

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# Extending $A_4$ 3HDM to Majorana neutrinos

Then, include Majorana neutrino terms:

$$c_{ij}^{ab} (L_i^T \tilde{\Phi}_a^*) \mathcal{C} (\tilde{\Phi}_b^\dagger L_j).$$

Group-theoretically, we see

$$(L \otimes L) \otimes (\underbrace{\tilde{\Phi}}_3 \otimes \underbrace{\tilde{\Phi}}_3)$$

Since  $\overline{L}_i \sim (1, 1', 1'')$ , the product  $L \otimes L$  also contains 1, 1', and 1'', which are coupled to  $3 \otimes 3$ :

$$\begin{aligned} & \frac{g_1}{\Lambda} (L_1 L_1 + L_2 L_3 + L_3 L_2) (\tilde{\Phi}_1 \tilde{\Phi}_1 + \tilde{\Phi}_2 \tilde{\Phi}_2 + \tilde{\Phi}_3 \tilde{\Phi}_3) \\ + & \frac{g_2}{\Lambda} (L_1 L_2 + L_2 L_1 + L_3 L_3) (\tilde{\Phi}_1 \tilde{\Phi}_1 + \omega \tilde{\Phi}_2 \tilde{\Phi}_2 + \omega^2 \tilde{\Phi}_3 \tilde{\Phi}_3) \\ + & \frac{g_3}{\Lambda} (L_1 L_3 + L_2 L_2 + L_3 L_1) (\tilde{\Phi}_1 \tilde{\Phi}_1 + \omega^2 \tilde{\Phi}_2 \tilde{\Phi}_2 + \omega \tilde{\Phi}_3 \tilde{\Phi}_3) \end{aligned}$$

# Extending $A_4$ 3HDM to Majorana neutrinos

Next, substituting the chosen vev alignment  $(1, 1, 1)$ , we get neutrino mass matrix:

$$\mathcal{M}_\nu = \frac{g_1 v^2}{2\Lambda} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix}.$$

We obtain **three degenerate neutrinos!**

## Conclusion

extending  $A_4$  symmetry to charged leptons and Majorana neutrinos with irrep assignment

$$\Phi \sim 3, \quad L \sim (1, 1', 1''), \quad \ell_R \sim 3$$

and with the vev alignment  $\langle \phi^0 \rangle = v(1, 1, 1)$  is **ruled out** by experiment.

# Extending $A_4$ 3HDM to Majorana neutrinos

One needs to check all possible irrep assignments and all possible vev alignments. This was done in [Gonzales Felipe, Serodio, Silva, 2013].

The result is: **all possible combinations are ruled out experimentally.** The problems can be:

- massless charged leptons,
- degenerate neutrino masses,
- insufficient neutrino mixing.

Thus, 3HDM scalar sector offers **too little freedom** to produce viable Majorana neutrino masses through the  $A_4$  symmetry group.

One needs to **enlarge the scalar sector** to get a viable neutrino sector.

# Extending $A_4$ 3HDM to Majorana neutrinos

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One needs to **enlarge the scalar sector** to get a viable neutrino sector.

# TBM PMNS from $A_4$ symmetry

# Classic seesaw again

Leptonic Yukawas:

$$\begin{aligned} & \bar{L}_i Y_{ij}^{\ell} \Phi \ell_{Rj} + \bar{L}_i Y_{ij}^{\nu} \tilde{\Phi} \nu_{Rj} + \frac{1}{2} \overline{(\nu_{Ri})^c} (M_R)_{ij} \nu_{Rj} + h.c. \\ = & \bar{\ell}_L M_{\ell} \ell_R + \frac{1}{2} \left[ \overline{\nu_L}, \overline{(\nu_R)^c} \right] \begin{pmatrix} 0 & m_D \\ m_D^T & M_R \end{pmatrix} \begin{pmatrix} (\nu_L)^c \\ \nu_R \end{pmatrix} + h.c. \end{aligned}$$

which leads to

$$\mathcal{M}_{\nu} = -m_D (M_R)^{-1} m_D^T.$$

The classic seesaw does not constrain matrices  $m_D$  and  $M_R \rightarrow$  no predictions on  $\mathcal{M}_{\nu} \rightarrow$  **no predictions on  $U_{PMNS}$ .**

# Flavons

Flavor symmetry-based modes assume that  $L_i$ ,  $(\ell_R)_i$ , and  $(\nu_R)_i$  transform in certain way under a discrete flavor symmetry group  $G$ .

Problem: combining  $L$ ,  $\ell_R$ , and  $\nu_R$ , via only Higgs doublets leads to contradiction to experiment!

Recipe: **leave the poor  $\Phi$  alone!** Add flavons  $\varphi_a$ : new auxiliary scalar fields, which will take care of the shape of the fermion sector.

# Flavons

## Flavons

- EW singlets  $\rightarrow$  play no role in electroweak symmetry breaking;
- transform non-trivially under  $G$ :

instead of  $Y_{ij}\bar{L}_i\Phi\ell_{Rj}$  we use  $Y_{ij}^a\frac{\varphi_a}{\Lambda}(\bar{L}_i\Phi\ell_{Rj})$ .

Symmetry under  $G$  **strongly constraints**  $Y_{ij}^a$ .

- they get vev after minimization of flavon scalar potential  $\varphi_a \rightarrow \langle\varphi_a\rangle \rightarrow$  spontaneous breaking of flavor symmetry **induces usual Yukawa interactions**

$$Y_{ij} = \sum_a Y_{ij}^a \frac{\langle\varphi_a\rangle}{\Lambda}.$$

with the resulting  $Y_{ij}$  **constrained by flavor symmetry**.

# $A_4$ symmetric model

	$\bar{L}$	$e_R$	$\mu_R$	$\tau_R$	$\nu_R$	$\Phi$	$\varphi_T$	$\varphi_S$	$\xi$
$SU(2)_L$	$\bar{2}$	1	1	1	1	2	1	1	1
$A_4$	3	1	1'	1''	3	1	3	3	1

We assume:

- LH doublets  $L$  and RH neutrinos  $\nu_R$  form  $A_4$  triplets;
- right charged leptons  $e_R, \mu_R, \tau_R$  form three different  $A_4$  singlets  $1, 1', 1''$ ;
- add three sorts of flavons:
  - $A_4$ -triplet  $\varphi_T$  helps join  $L$  with  $\ell_R$  ( $\rightarrow$  charged lepton masses),
  - $A_4$ -triplet  $\varphi_S$  produces one Majorana term for  $\nu_R$ ,
  - $A_4$ -singlet  $\xi$  produces another Majorana term for  $\nu_R$ .

# $A_4$ symmetric model

**Warning:** this construction is not yet self-consistent! So far nothing explains why  $\varphi_T$  and  $\varphi_S$  play different roles!

To forbid “wrong terms”, we introduce yet another quantum number: “charge” under the group  $\mathbb{Z}_3$ .

	$\bar{L}$	$e_R$	$\mu_R$	$\tau_R$	$\nu_R$	$\Phi$	$\varphi_T$	$\varphi_S$	$\xi$
$SU(2)_L$	$\bar{2}$	1	1	1	1	2	1	1	1
$A_4$	3	1	1'	1''	3	1	3	3	1
$\mathbb{Z}_3$	$\omega^2$	$\omega$	$\omega$	$\omega$	$\omega$	1	1	$\omega$	$\omega$

The true symmetry group of the model is  $A_4 \times \mathbb{Z}_3$  but I will skip  $\mathbb{Z}_3$  for clarity.

# $A_4$ symmetric model

TMB mixing from  $A_4$  symmetry [Altarelli, Feruglio, 2006]

	$\bar{L}$	$e_R$	$\mu_R$	$\tau_R$	$\nu_R$	$\Phi$	$\varphi_T$	$\varphi_S$	$\xi$
$SU(2)_L$	$\bar{2}$	1	1	1	1	2	1	1	1
$A_4$	3	1	1'	1''	3	1	3	3	1

$\mathcal{L}$  = charged leptons separately for  $e$ ,  $\mu$ , and  $\tau$   
 + Dirac mass term + two Majorana mass terms

$$= \frac{y_e}{\Lambda} \underbrace{(\bar{L}\varphi_T)}_{3 \times 3 \rightarrow 1} \underbrace{e_R}_1 \Phi + \frac{y_\mu}{\Lambda} \underbrace{(\bar{L}\varphi_T)}_{3 \times 3 \rightarrow 1''} \underbrace{\mu_R}_{1'} \Phi + \frac{y_\tau}{\Lambda} \underbrace{(\bar{L}\varphi_T)}_{3 \times 3 \rightarrow 1'} \underbrace{\tau_R}_{1''} \Phi$$

$$+ y_D \underbrace{(\bar{L}\nu_R)}_{3 \times 3 \rightarrow 1} \tilde{\Phi} + y_a \underbrace{(\nu_R\nu_R)}_{(3 \times 3)_{1 \times 1}} \xi + y_b \underbrace{(\nu_R\nu_R\varphi_S)}_{3 \times 3 \times 3 \rightarrow 1} + h.c.$$

# $A_4$ symmetric model

It is convenient to work in the  $T$ -diagonal basis  $\rightarrow$  charged lepton mass matrix will be diagonal.

Contractions written explicitly (for explicit expressions, see e.g. [Altarelli, Feruglio, 1002.0211]):

$$\begin{aligned}(\bar{\ell}_L \varphi_T)_1 &= \bar{e}_L(\varphi_T)_1 + \bar{\mu}_L(\varphi_T)_3 + \bar{\tau}_L(\varphi_T)_2 \\(\bar{\ell}_L \varphi_T)_{1''} &= \bar{e}_L(\varphi_T)_2 + \bar{\mu}_L(\varphi_T)_1 + \bar{\tau}_L(\varphi_T)_3 \\(\bar{\ell}_L \varphi_T)_{1'} &= \bar{e}_L(\varphi_T)_3 + \bar{\mu}_L(\varphi_T)_2 + \bar{\tau}_L(\varphi_T)_1\end{aligned}$$

and  $(\nu_R \nu_R \varphi_S)_1$  gives

$$\nu_{Ri} \left[ \begin{pmatrix} 2 & 0 & 0 \\ 0 & 0 & -1 \\ 0 & -1 & 0 \end{pmatrix} \varphi_{S1} + \begin{pmatrix} 0 & 0 & -1 \\ 0 & 2 & 0 \\ -1 & 0 & 0 \end{pmatrix} \varphi_{S2} + \begin{pmatrix} 0 & -1 & 0 \\ -1 & 0 & 0 \\ 0 & 0 & 2 \end{pmatrix} \varphi_{S3} \right] \nu_{Rj}$$

# Flavons alignment

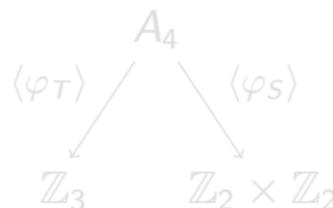
The flavon potential is also  $A_4$  symmetric and has “Mexican hat” form. It produces nonzero vevs with the following alignment:

$$\langle \varphi_T \rangle \propto (1, 0, 0), \quad \langle \varphi_S \rangle \propto (1, 1, 1), \quad \langle \xi \rangle \neq 0.$$

This is the **vev alignment** which we **postulate** when building our model.

$$S = \frac{1}{3} \begin{pmatrix} -1 & 2 & 2 \\ 2 & -1 & 2 \\ 2 & 2 & -1 \end{pmatrix}, \quad T = \begin{pmatrix} 1 & 0 & 0 \\ 0 & \omega & 0 \\ 0 & 0 & \omega^2 \end{pmatrix}, \quad \omega \equiv e^{2\pi i/3}.$$

- $\langle \varphi_T \rangle$  conserves  $T$  (subgroup  $\mathbb{Z}_3$ ),
- $\langle \varphi_S \rangle$  conserves  $S$  (and  $TST^2$ , subgroup  $\mathbb{Z}_2 \times \mathbb{Z}_2$ ).



# Flavons alignment

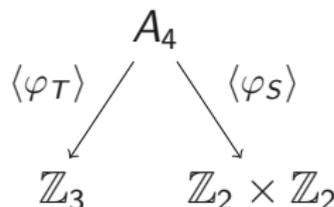
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# Consequences of flavons alignment

Charged leptons  $\langle \varphi_T \rangle \sim (1, 0, 0)$ :

$$\frac{y_e}{\Lambda} (\bar{L} \varphi_T) e_R \Phi + \frac{y_\mu}{\Lambda} (\bar{L} \varphi_T) \mu_R \Phi + \frac{y_\tau}{\Lambda} (\bar{L} \varphi_T) \tau_R \Phi$$

$$\rightarrow \frac{\langle \varphi_T \rangle}{\Lambda} (y_e \bar{L}_e e_R + y_\mu \bar{L}_\mu \mu_R + y_\tau \bar{L}_\tau \tau_R) \Phi + h.c.$$

$$\rightarrow (\bar{e}_L, \bar{\mu}_L, \bar{\tau}_L) \begin{pmatrix} m_e & 0 & 0 \\ 0 & m_\mu & 0 \\ 0 & 0 & m_\tau \end{pmatrix} \begin{pmatrix} e_R \\ \mu_R \\ \tau_R \end{pmatrix} + h.c.$$

Charged lepton mass matrix is automatically **diagonal**.

# Consequences of flavons alignment

Dirac mass matrix:

$$y_D(\bar{L}\nu_R)\tilde{\Phi} = y_D\bar{\nu}_{Li} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix} \nu_{Rj}\tilde{\Phi},$$

which after EWSB gives  $\bar{\nu}_{Li}(m_D)_{ij}\nu_{Rj}$  with

$$m_D = \frac{y_D v}{\sqrt{2}} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix}.$$

# Consequences of flavons alignment

Majorana mass matrix for  $\nu_R$ :

$$\begin{aligned}
 M_R &= y_a \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix} \langle \xi \rangle \\
 &+ y_b \left[ \begin{pmatrix} 2 & 0 & 0 \\ 0 & 0 & -1 \\ 0 & -1 & 0 \end{pmatrix} \langle \varphi_{S1} \rangle + \begin{pmatrix} 0 & 0 & -1 \\ 0 & 2 & 0 \\ -1 & 0 & 0 \end{pmatrix} \langle \varphi_{S2} \rangle + \begin{pmatrix} 0 & -1 & 0 \\ -1 & 0 & 0 \\ 0 & 0 & 2 \end{pmatrix} \langle \varphi_{S3} \rangle \right] \\
 &= a \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix} + b \begin{pmatrix} 2 & -1 & -1 \\ -1 & 2 & -1 \\ -1 & -1 & 2 \end{pmatrix}.
 \end{aligned}$$

# Consequences of flavons alignment

Overall result:

$$\mathcal{M}_\nu = -m_D(M_R)^{-1}m_D^T,$$

where

$$m_D = \frac{y_{DV}}{\sqrt{2}} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix}, \quad M_R = \begin{pmatrix} a+2b & -b & -b \\ -b & 2b & a-b \\ -b & a-b & 2b \end{pmatrix}.$$

Then we will need to diagonalize it:

$$D_\nu = U^T \mathcal{M}_\nu U,$$

and, since the charged lepton matrix is already diagonal,

$$U_{PMNS} = U.$$

# Inverting $M_R$

The simple form of

$$M_R = \begin{pmatrix} a + 2b & -b & -b \\ -b & 2b & a - b \\ -b & a - b & 2b \end{pmatrix}.$$

allows to explicitly calculate eigenvalues and eigenvectors:

$$\lambda = 3b + a, \quad \vec{v} = \frac{1}{\sqrt{6}} \begin{pmatrix} 2 \\ -1 \\ -1 \end{pmatrix},$$

$$\lambda = a, \quad \vec{v} = \frac{1}{\sqrt{3}} \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix},$$

$$\lambda = 3b - a, \quad \vec{v} = \frac{1}{\sqrt{2}} \begin{pmatrix} 0 \\ 1 \\ -1 \end{pmatrix}.$$

# Inverting $M_R$

This means that

$$\begin{pmatrix} \sqrt{\frac{2}{3}} & -\frac{1}{\sqrt{6}} & -\frac{1}{\sqrt{6}} \\ \frac{1}{\sqrt{3}} & \frac{1}{\sqrt{3}} & \frac{1}{\sqrt{3}} \\ 0 & \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} \end{pmatrix} \begin{pmatrix} a+2b & -b & -b \\ -b & 2b & a-b \\ -b & a-b & 2b \end{pmatrix} \begin{pmatrix} \sqrt{\frac{2}{3}} & \frac{1}{\sqrt{3}} & 0 \\ -\frac{1}{\sqrt{6}} & \frac{1}{\sqrt{3}} & \frac{1}{\sqrt{2}} \\ -\frac{1}{\sqrt{6}} & \frac{1}{\sqrt{3}} & -\frac{1}{\sqrt{2}} \end{pmatrix} \\ = \begin{pmatrix} 3b+a & 0 & 0 \\ 0 & a & 0 \\ 0 & 0 & 3b-a \end{pmatrix}$$

Or, in short,

$$U^T M_R U = D_R \quad \Leftrightarrow \quad U D_R U^T = M_R.$$

Calculating  $\mathcal{M}_\nu$ 

Therefore,

$$M_R^{-1} = UD_R^{-1}U^T = U \begin{pmatrix} \frac{1}{3b+a} & 0 & 0 \\ 0 & \frac{1}{a} & 0 \\ 0 & 0 & \frac{1}{3b-a} \end{pmatrix} U^T.$$

The light neutrino mass matrix is therefore

$$\begin{aligned} \mathcal{M}_\nu &= m_D M_R^{-1} m_D^T = m_D \cdot UD_R^{-1}U^T \cdot m_D^T \\ &= U \cdot U^T m_D U \cdot D_R^{-1} \cdot U^T m_D^T U \cdot U^T. \end{aligned}$$

We need to calculate  $U^T m_D U$ .

# Calculating $\mathcal{M}_\nu$

Notice that

$$m_D = \frac{y_{DV}}{\sqrt{2}} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix},$$

is exactly like the  $a$ -term of  $M_R$ . Therefore,

$$U^T m_D U = \frac{y_{DV}}{\sqrt{2}} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -1 \end{pmatrix}.$$

Overall result:

$$\mathcal{M}_\nu = U(U^T m_D U) D_R^{-1} (U^T m_D^T U) U^T = \frac{y_D^2 v^2}{2} U D_R^{-1} U^T.$$

# Consequences

$$\mathcal{M}_\nu = \frac{y_D^2 v^2}{2} U \begin{pmatrix} \frac{1}{3b+a} & 0 & 0 \\ 0 & \frac{1}{a} & 0 \\ 0 & 0 & \frac{1}{3b-a} \end{pmatrix} U^T.$$

- $U$  diagonalizes  $\mathcal{M}_\nu \rightarrow U = U_{PMNS}$  is of the TBM form;
- neutrino masses are:

$$m_1 = \frac{y_D^2 v^2}{3b+a}, \quad m_2 = \frac{y_D^2 v^2}{a}, \quad m_3 = \frac{y_D^2 v^2}{3b-a}.$$

Very heavy flavon parameters  $a, b \rightarrow$  very light neutrinos.

- mass sum rule:

$$\frac{1}{m_3} = \frac{1}{m_1} - \frac{2}{m_2}.$$

which is a prediction of the  $A_4$  model! Be careful:  $a$  and  $b$  are complex.

- both NO and IO are possible; the sum rule **implies a lower bound!**

# Consequences

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# Other symmetry groups

This is a typical symmetry-based recipe:

- pick up  $G$ , select irreps for  $L$ ,  $\ell_R$ ,  $\nu_R$ , add flavons at will;
- choose flavon vev alignment among possible choices;
- calculate  $M_\ell$ ,  $m_D$ ,  $M_R \rightarrow$  calculate  $\mathcal{M}_\nu$ ;
- (analytically) diagonalize  $M_\ell$ ,  $\mathcal{M}_\nu \rightarrow$  derive  $U_{PMNS}$ ;
- derive sum rule for  $m_{1,2,3}$ .

Many series of finite groups have been studied [[Holthausen, Lim, Lindner, 2012](#)] and some are close to the experimental PMNS matrix.